

ADMISSIBILITY OF PREDICTION REGIONS IN TWO-DIMENSIONAL NORMAL DISTRIBUTION

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1. Introduction

Suppose that X and Y are independently and identically distributed p -dimensional normal random vectors with mean θ and covariance matrix equal to the identity matrix I_p ($N_p(\theta, I_p)$). This paper deals with the problem of predicting Y by using a region based on the observed value of X which is called a prediction region.

A prediction region $S(X)$ is evaluated by its coverage probability $P_\theta\{Y \in S(X)\}$ and its volume with respect to Lebesgue measure μ . The larger its coverage probability and the smaller its volume are, the better the prediction region is. Given a prediction region $S(X)$, consider a function ϕ defined by

$$\phi(x, y) = \begin{cases} 1, & \text{if } y \in S(x), \\ 0, & \text{otherwise.} \end{cases}$$

Then it holds that

$$(1.1) \quad P_\theta\{Y \in S(X)\} = E_\theta\{\phi(X, Y)\}.$$

and

$$(1.2) \quad E_\theta\{\mu(S(X))\} = E_\theta\left\{\int \phi(X, y)dy\right\},$$

where $\mu(S(X))$ denotes the volume of $S(X)$. Conversely, every function ϕ with $0 \leq \phi(x, y) \leq 1$ define a prediction procedure by which a randomized prediction region is constructed such that (1.1) and (1.2) are satisfied. In the sequel, prediction regions are randomized and identified with such a function ϕ .

Definition 1 A prediction region ϕ is admissible if there exists no other prediction region ϕ' such that for all θ

$$(1.3) \quad E_\theta\{\phi'(X, Y)\} \geq E_\theta\{\phi(X, Y)\}$$

and

$$(1.4) \quad E_{\theta} \left\{ \int \phi'(X, y) dy \right\} \leq E_{\theta} \left\{ \int \phi(X, y) dy \right\}$$

and the strict inequality holds for at least one θ in (1.3) or in (1.4).

Definition 2 A prediction region ϕ is minimax if

$$\sup_{\theta} E_{\theta} \left\{ \int \phi(X, y) dy \right\} \leq \sup_{\theta} E_{\theta} \left\{ \int \phi'(X, y) dy \right\}$$

for any prediction region ϕ' such that

$$\inf_{\theta} E_{\theta} \{ \phi'(X, Y) \} \geq \inf_{\theta} E_{\theta} \{ \phi(X, Y) \}.$$

The usual prediction region ϕ_0 is

$$(1.5) \quad S_0(x) = \{y; |x - y| < h\},$$

where $|x - y|$ denotes the Euclidian distance between x and y . It is easy to see that

$$(1.6) \quad E_{\theta} \left\{ \int \phi_0(X, y) dy \right\} = \frac{\pi^{p/2} h^p}{\Gamma(p/2 + 1)} = v \quad (\text{say})$$

and

$$(1.7) \quad E_{\theta} \{ \phi_0(X, Y) \} = \int_0^{h^2/2} \frac{t^{p/2-1} e^{-t/2}}{\Gamma(p/2) 2^{p/2}} dt = 1 - \alpha \quad (\text{say}).$$

From Theorem 2 of Takada [4] it turns out that ϕ_0 is the best invariant prediction region, that is, ϕ_0 uniformly minimizes (1.2) among the class of prediction regions such that

$$\phi(x + a, y + a) = \phi(x, y) \quad \text{for any } x, y \text{ and } a$$

and the coverage probabilities are not less than a specified value. In Section 2 we shall prove that ϕ_0 is minimax. We [5] proved the admissibility of ϕ_0 for $p = 1$. In Section 3 we shall prove the result for $p = 2$ by using the method of Joshi [3] to prove the admissibility of confidence regions. For $p \geq 3$ we conjecture that ϕ_0 is not admissible (cf. Joshi [2], Hwang and Casella [1]), but the result has not been proved yet.

2. Minimax Prediction Region

For any prediction region ϕ let

$$L_\phi(x, y) = b\phi(x, \cdot) - \phi(x, y),$$

where $\phi(x, \cdot) = \int \phi(x, y)dy$ and $b = (4\pi)^{-p/2} \exp(-h^2/4)$. Then

$$(2.1) \quad E_\theta\{L_\phi(X, Y)\} = bE_\theta\{\int \phi(X, y)dy\} - E_\theta\{\phi(X, Y)\}.$$

From (1.6) and (1.7) it follows that

$$(2.2) \quad E_\theta\{L_{\phi_0}(X, Y)\} = bv - (1 - \alpha).$$

Suppose that a prior distribution ξ of θ is $N_p(0, \tau I_p)$ and let

$$R(\tau, \phi) = \int \{E_\theta L_\phi(X, Y)\} \xi(d\theta).$$

Then it follows that

$$(2.3) \quad R(\tau, \phi) = \int f_\tau(x) \{ \int (b - f_\tau(y|x)) \phi(x, y) dy \} dx,$$

where $f_\tau(x)$ is the marginal density of X and $f_\tau(y|x)$ is the conditional density of Y given $X=x$. It is easy to see that the conditional distribution of Y given $X=x$ is $N_p(\mu(x), \rho I_p)$, where $\mu(x) = \tau x / (1 + \tau)$ and $\rho = (2\tau + 1) / (\tau + 1)$. Hence $f_\tau(y|x) > b$ if and only if $|y - \mu(x)| < c$, where $c^2 = p(2/k) \log k + h^2/k$ and $k = 2/\rho$. So the prediction region ϕ_τ given by

$$S_\tau(x) = \{y; |y - \mu(x)| < c\}$$

minimizes $R(\tau, \phi)$ among all prediction regions and

$$(2.4) \quad R(\tau, \phi_\tau) = \frac{bc^p \pi^{p/2}}{\Gamma(p/2 + 1)} - \int_0^{c^2/\rho} \frac{t^{p/2-1} e^{-t/2}}{\Gamma(p/2) 2^{p/2}} dt.$$

Theorem 1 *The usual prediction region ϕ_0 is minimax.*

Proof. From (2.2) and (2.4) it follows that

$$(2.5) \quad \lim_{\tau \rightarrow \infty} R(\tau, \phi_\tau) = bv - (1 - \alpha).$$

Since

$$\sup_{\theta} E_{\theta}\{L_{\phi}(X, Y)\} \geq R(\tau, \phi),$$

from (2.5) we get

$$(2.6) \quad \sup_{\theta} E_{\theta}\{L_{\phi}(X, Y)\} \geq bv - (1 - \alpha).$$

From the inequality that

$$\sup_{\theta} E_{\theta}\{L_{\phi}(X, Y)\} \leq b \sup_{\theta} E_{\theta}\left\{\int \phi(X, y) dy\right\} - \inf_{\theta} E_{\theta}\{\phi(X, Y)\}$$

and (2.6), it follows that if

$$\inf_{\theta}\{\phi(X, Y)\} \geq 1 - \alpha,$$

then

$$\sup_{\theta} E_{\theta}\left\{\int \phi(X, y) dy\right\} \geq v,$$

which completes the proof.

3. Admissibility

In this section we shall prove the admissibility of the usual prediction region ϕ_0 of (1.5) for $p = 2$. The method of the proof is almost the same as that of the proof of the admissibility of the usual confidence region given by Joshi [3].

From (2.4) we get

$$\begin{aligned} R(\tau, \phi_{\tau}) &= bc^2\pi - 1 + \exp(-kc^2/4) \\ &= bk^{-1}v + 4\pi bk^{-1} \log k - 1 + k^{-1}\alpha. \end{aligned}$$

Since $k > 1$ and $1 - k^{-1} < (2\tau)^{-1}$, from (2.2)

$$(3.1) \quad R(\tau, \phi_0) - R(\tau, \phi_{\tau}) < (bv + \alpha)/(2\tau).$$

Theorem 2 *The usual prediction region ϕ_0 is admissible for $p = 2$.*

Proof. Suppose that there exists a prediction region ϕ_1 such that for all θ

$$E_{\theta}\{\phi_1(X, Y)\} \geq 1 - \alpha$$

and

$$E_{\theta}\left\{\int \phi_1(X, y)dy\right\} \leq v.$$

Then from (2.1) we get

$$E_{\theta}\{L_{\phi_1}(x, Y)\} \leq E_{\theta}\{L_{\phi_0}(X, Y)\}$$

for all θ , so that for any τ

$$(3.2) \quad R(\tau, \phi_1) \leq R(\tau, \phi_0).$$

Let $f(x, y) = (4\pi)^{-1} \exp\{-|x - y|^2/4\}$. Then it follows from (1.5) that

$$(3.3) \quad \phi_0(x, y) = \begin{cases} 1, & \text{if } f(x, y) > b, \\ 0, & \text{otherwise.} \end{cases}$$

Define two functions by

$$U_i(x) = b\phi_i(x, \cdot) - \int \phi_i(x, y)f(x, y)dy, \quad i = 0, 1.$$

Then we get

$$(3.4) \quad U_1(x) - U_0(x) = \int (b - f(x, y))(\phi_1(x, y) - \phi_0(x, y))dy,$$

and hence from (3.3)

$$(3.5) \quad U_1(x) \geq U_0(x) \quad \text{for any } x$$

Let

$$M = \int (U_1(x) - U_0(x))dx.$$

Then $0 \leq M \leq \infty$. We shall prove that $M < \infty$.

Since the marginal distribution of X is $N_2(0, (1 + \tau)I_2)$, from (2.3) we get

$$(3.6) \quad R(\tau, \phi_1) - R(\tau, \phi_0) = (2\pi(1 + \tau))^{-1} \int G_{\tau}(x)dx,$$

where

$$\begin{aligned} G_{\tau}(x) &= \exp\{-|x|^2/(2(1 + \tau))\} \{ [b\phi_1(x, \cdot) - \int \phi_1(x, y)f_{\tau}(y|x)dy] \\ &\quad - [b\phi_0(x, \cdot) - \int \phi_0(x, y)f_{\tau}(y|x)dy] \} \end{aligned}$$

It is easy to see that

$$\lim_{\tau \rightarrow \infty} G_\tau(x) = U_1(x) - U_0(x)$$

and

$$\begin{aligned} |G_\tau(x)| &\leq b\phi_1(x, \cdot) + 2 + b\nu \\ &= G(x) \quad (\text{say}). \end{aligned}$$

Let $T_a = \{x; |x| \leq a\}$. Then

$$\int_{T_a} G(x) dx \leq (b\nu + 2)\pi a^2 + b \int_{T_a} \phi_1(x, \cdot) dx$$

and

$$\begin{aligned} \int_{T_a} \phi_1(x, \cdot) dx &\leq 2\pi e^{a^2/2} b \int_{T_a} \phi_1(x, \cdot) p_0(x) dx \\ &\leq 2\pi e^{a^2/2} b\nu, \end{aligned}$$

where $p_0(x) = (2\pi)^{-1} \exp(-|x|^2/2)$. So we get

$$\int_{T_a} G(x) dx < \infty.$$

By the dominated convergence theorem

$$\begin{aligned} \lim_{\tau \rightarrow \infty} \int_{T_a} G_\tau(x) dx &= \int_{T_a} (U_1(x) - U_0(x)) dx \\ &= k_a \quad (\text{say}), \end{aligned}$$

which implies that for any $\epsilon > 0$ there exists τ_0 such that

$$(3.7) \quad \int_{T_a} G_\tau(x) dx \geq k_a - \epsilon \quad \text{for } \tau \geq \tau_0$$

Since for any prediction region ϕ

$$b\phi(x, \cdot) - \int \phi(x, y) f_\tau(y|x) dy \geq b\phi_\tau(x, \cdot) - \int \phi_\tau(x, y) f_\tau(y|x) dy,$$

we get

$$(2\pi(1+\tau))^{-1} \int_{T_a^\epsilon} G_\tau(x) dx$$

$$\begin{aligned} &\geq (2\pi(1 + \tau))^{-1} \int_{T_a^c} \exp(-|x|^2/2(1 + \tau)) \{ [b\phi_\tau(x, \cdot) \\ &- \int \phi_\tau(x, y) f_\tau(y|x) dy] - [b\phi_0(x, \cdot) - \int \phi_0(x, y) f_\tau(y|x) dy] \} dx \\ &\geq R(\tau, \phi_\tau) - R(\tau, \phi_0) \\ &\geq -(bv + \alpha)/(2\tau), \end{aligned}$$

where the last inequality follows from (3.1). Hence from (3.6) and (3.7) for $\tau \geq \tau_0$

$$R(\tau, \phi_1) - R(\tau, \phi_0) \geq \frac{k_a - \epsilon}{2\pi(1 + \tau)} - \frac{bv + \alpha}{2\tau},$$

so that from (3.2)

$$\frac{\pi(1 + \tau)(bv + \alpha)}{\tau} + \epsilon \geq k_a,$$

and hence for any $a > 0$

$$k_a \leq 2\pi(bv + \alpha).$$

Therefore

$$\lim_{a \rightarrow \infty} \int_{T_a} (U_1(x) - U_0(x)) dx = M < \infty.$$

It can be shown that $M = 0$, but the proof is tedious and so is omitted. See the section 6 of Joshi [3]. Hence from (3.5)

$$U_1(x) = U_0(x) \quad a.e..$$

It follows from (3.4) that

$$\begin{aligned} U_1(x) - U_0(x) &= \int_{S_0(x)} (f(x, y) - b)(1 - \phi_1(x, y)) dy \\ &+ \int_{S_0(x)^c} (b - f(x, y)) \phi_1(x, y) dy, \end{aligned}$$

and hence from (3.3) for any x

$$\phi_1(x, y) = \phi_0(x, y) \quad a.e. \quad y.$$

Therefore by Fubini's theorem

$$\phi_1(x, y) = \phi_0(x, y) \quad a.e.,$$

which completes the proof.

References

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