

STABILITY OF SPATIO-TEMPORAL OSCILLATIONS OF DIFFUSIVE LOTKA-VOLTERRA SYSTEM

Dedicated to Professor Kenzo Iizuka on his 60th birthday

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In [2] K. Kishimoto, M. Mimura and K. Yoshida gave some examples of diffusive Lotka-Volterra system with three or more species which exhibits stable spatio-temporal oscillatory phenomena. We employed there the bifurcation technique and evaluated the "stability constant K " which was defined by S.-N. Chow and J. Mallet-Paret in [1]. Since the calculation of K in [2] was long, we only gave the final result. Thus in this note we not only give a detailed calculation of K but also show the existence of the center manifold, from which the Hopf bifurcation theorem follows easily.

The system which we consider in this note is the diffusive Lotka-Volterra system parameterized by α in one dimensional interval;

$$(0.1) \quad \begin{aligned} \dot{u}_i(t, x) &= \sigma_i(\alpha)(u_i)_{xx}(t, x) + (r_i + \sum_{j=1}^d a_{ij}u_j(t, x))u_i(t, x) \\ 0 < x < \pi, t > 0, i &= 1, \dots, d \end{aligned}$$

subject to

$$(0.2) \quad (u_i)_x(t, 0) = (u_i)_x(t, \pi) = 0,$$

where $\dot{} = d/dt$. Here $u_i(t, x)$ is the density of the i -th species at time t and at position x . The diffusion coefficients $\sigma_i(\alpha)$ are positive constants. The diagonal coefficients a_{ii} are nonpositive constants, which reflects intraspecific competition, while the off-diagonal coefficients $a_{ij}(i \neq j)$ are real constants. This means that the interspecific relations may be competitive, cooperative, prey-predator type or combinations.

1. Decomposition of the system

Assume that (0.1) has a constant equilibrium solution

$$\bar{U} = \text{col} (\bar{u}_1, \bar{u}_2, \dots, \bar{u}_d), \quad \bar{u}_j > 0,$$

where $\text{col} (\dots)$ means a column vector. Then, (0.1) is written as

$$\dot{u}_i = \sigma_i(\alpha)(u_i)_{xx} + \sum_{j=1}^d a_{ij}(u_j - \bar{u}_j)u_i,$$

which is rewritten as

$$(1.1) \quad \dot{U} = D(\alpha)U_{xx} + A(\bar{U})U + N(U),$$

if u_i is replaced by $u_i - \bar{u}_i$ and we use the vector notation : $U = \text{col} (u_1, \dots, u_d)$, $D(\alpha)$ is the $d \times d$ diagonal matrix whose (i, i) -components are $\sigma_i(\alpha)$, $A(\bar{U})$ is the $d \times d$ matrix whose (i, j) -components are $-a_{ij}\bar{u}_i$ and

$$N(U) = \text{col} (n_1(u_1, \dots, u_d), \dots, n_d(u_1, \dots, u_d))$$

with

$$n_i(u_1, \dots, u_d) = \sum_{j=1}^d a_{ij}u_i u_j.$$

Let us now consider the eigenvalue problem for the linear part of (1.1) with zero Neumann boundary condition;

$$(1.2) \quad \begin{cases} \lambda V(x) = D(\alpha)V_{xx}(x) + A(\bar{U})V(x) \\ V_x(0) = V_x(\pi) = 0 \end{cases}$$

If we take the Fourier expansion

$$V(x) = \sum_{n=0}^{\infty} \Phi_n \cos nx$$

with constant vectors

$$\Phi_n = \text{col} (\Phi_{n1}, \dots, \Phi_{nd}),$$

then the eigenvalue problem (1.2) is equivalent to the one

$$(1.3) \quad \lambda \Phi_n = (A(\bar{U}) - n^2 D(\alpha))\Phi_n, \quad n = 0, 1, \dots$$

Throughout this note we assume that

(H.1) for some $n=n_0$ there exists a real number $\delta > 0$ such that, for any α with $-\delta < \alpha < \delta$, the eigenvalue problem (1.3) has a unique pair of complex conjugate eigenvalues $\lambda(\alpha)$ and $\overline{\lambda(\alpha)}$ such that

$$\lambda(\alpha) = \mu(\alpha) + i\omega(\alpha) = \omega_0 > 0,$$

$$\mu(0) = 0, \mu'(0) \neq 0,$$

where $\mu'(\alpha)$ is the derivative with respect to α ,

(H.2) all the eigenvalues except for $\lambda(\alpha)$ and $\overline{\lambda(\alpha)}$ have strictly negative real part for any n .

Under these assumption we have the spectral decomposition

$$L^2([0, \pi]) = P \oplus Q,$$

where $L^2([0, \pi]) = (L^2([0, \pi]))^d$ and P it the two-dimensional eigenspace corresponding to the eigenvalues $\lambda(\alpha)$ and $\overline{\lambda(\alpha)}$.

In what follows we decompose the system (1.1) into the one restricted to P and the other. Let Φ_{n_0} be the eigenvector corresponding to $\lambda(\alpha)$ and put

$$\Phi = \text{col}(\Phi_1, \dots, \Phi_d) = \text{Re } \Phi_{n_0} \text{ and } \Psi = \text{col}(\Psi_1, \dots, \Psi_d) = \text{Im } \Phi_{n_0}.$$

Then Φ and Ψ are linearly independent but not necessarily orthogonal.

Let us put

$$(1.4) \quad U(t, x) = z(t)\Phi_{n_0} \cos n_0 x + \overline{z(t)}\overline{\Phi_{n_0}} \cos n_0 x + W(t, x)$$

with a complex valued scalar function

$$z(t) = u(t) + iv(t)$$

and define the projection Π from $L^2([0, \pi])$ to P by

$$\Pi[V(\cdot)] = \Pi_1[V]\Phi \cos n_0 x + \Pi_2[V]\Psi \cos n_0 x$$

with

$$\Pi[V] = e_1 \left\langle \int_0^\pi V(x) \cos n_0 x dx, \Phi \right\rangle + e_2 \left\langle \int_0^\pi V(x) \cos n_0 x dx, \Psi \right\rangle,$$

$$\Pi_2[V] = e_2 \left\langle \int_0^\pi V(x) \cos n_0 x dx, \Phi \right\rangle + e_3 \left\langle \int_0^\pi V(x) \cos n_0 x dx, \Psi \right\rangle,$$

where $\langle \cdot, \cdot \rangle$ stands for the scalar product in \mathbf{R}^d ,

$$\dot{d}x = \frac{2}{\pi} dx,$$

$$\begin{aligned} e_1 &= \langle \Psi, \Psi \rangle / (\langle \Phi, \Phi \rangle \langle \Psi, \Psi \rangle - \langle \Phi, \Psi \rangle^2), \\ e_2 &= -\langle \Phi, \Psi \rangle / (\langle \Phi, \Phi \rangle \langle \Psi, \Psi \rangle - \langle \Phi, \Psi \rangle^2), \\ e_3 &= \langle \Phi, \Phi \rangle / (\langle \Phi, \Phi \rangle \langle \Psi, \Psi \rangle - \langle \Phi, \Psi \rangle^2). \end{aligned}$$

Insert (1.4) into (1.1) and apply Π to the both sides. Then we have

$$(1.6) \quad \begin{cases} \dot{u}(t) = \mu(\alpha)u(t) - \omega(\alpha)v(t) + \frac{1}{2} \Pi_1[N(U)], \\ \dot{v}(t) = \omega(\alpha)u(t) + \mu(\alpha)v(t) - \frac{1}{2} \Pi_2[N(U)], \\ \dot{W} = D(\alpha)W_{xx} + A(\bar{U}) + [1 - \Pi][N(U)]. \end{cases}$$

2. The center manifold and the Hopf bifurcation

Let $\mathbf{H}^2([0, \pi])$ be the space of real vector valued L^2 functions whose derivatives of order up to two belong to $L^2([0, \pi])$ and put $\mathbf{H}_N^2([0, \pi]) = \{V \in \mathbf{H}^2([0, \pi]); V_x(0) = V_x(\pi) = 0\}$. Then by the same way as in [3] we have

THEOREM 1. *Let k be an arbitrary fixed positive integer. Then there exist a zero neighborhood $\mathcal{U} \times I$ in $\mathbf{R}^2 \times (-\delta, \delta)$ and a k times continuously differentiable function G on $\mathcal{U} \times I$ with values in $Q \cap \mathbf{H}_N^2$ satisfying the following conditions:*

- i) $G(0, 0, \alpha) = 0$, $(\partial G / \partial x_1)(0, 0, 0) = (\partial G / \partial x_2)(0, 0, 0) = 0$
- ii) for any $\alpha \in I$, let

$$\mathcal{M}(\alpha) = \{V \in \mathbf{H}_N^2; V(x) = u\Phi \cos n_0 x + v\Psi \cos n_0 x + G(u, v, \alpha), (u, v) \in \mathcal{U}\}.$$

Then $\mathcal{M}(\alpha)$ is locally invariant in the sense that if, for any $V \in \mathcal{M}(\alpha)$ such that $(\Pi_1[V], \Pi_2[V]) \in \mathcal{U}$, the solution $(u(t), v(t))$ of

$$\dot{u}(t) = \mu(\alpha)u(t) - \omega(\alpha)v(t) + \frac{1}{2} \Pi_1[N(U_G)]$$

$$\dot{v}(t) = \omega(\alpha)u(t) + \mu(\alpha)v(t) - \frac{1}{2} \Pi_2 [N(U_G)]$$

with

$$u(0) = \frac{1}{2} \Pi_1 [V], \quad v(0) = -\frac{1}{2} \Pi_2 [V],$$

$$U_G(t, x) = z(t)\Phi_{n_0} \cos n_0x + \overline{z(t)} \bar{\Phi}_{n_0} \cos n_0x + G(u(t), v(t), \alpha),$$

$$z(t) = u(t) + iv(t)$$

stays in \mathcal{U} , then $U_G(t, x)$ defined as above with the solution $(u(t), v(t))$ is the unique solution of (1.1) with zero Neumann boundary condition.

$\mathcal{H}(\alpha)$ is locally attractive, that is, if the solution $U(t, x)$ of (1.1) with zero Neumann boundary condition satisfies $(\Pi_1 [U(t, \cdot)], \Pi_2 [U(t, \cdot)]) \in \mathcal{U}$ for $0 \leq t < T$, then there exist positive constants C and γ independent of t such that

$$\|U(t, \cdot) - \Pi [U(t, \cdot)] - G(u(t), v(t), \alpha)\|_{H^2} \leq Ce^{-\gamma t} \|U(0, \cdot)\|_{H^2},$$

where $u(t) = \Pi_1 [U(t, \cdot)]$ and $v(t) = \Pi_2 [U(t, \cdot)]$.

From Theorem 1 we have, easily,

THEOREM 2. *Under the assumption (H.1) and (H.2) the spatially inhomogeneous Hopf bifurcation occurs at $\alpha = 0$.*

3. Calculation of stability constant K

As is stated in Introduction, we make use of S.-N. Chow and J. Mallet-Paret's theory in order to investigate the stability of the Hopf bifurcation. To do so let us remember their theory.

Let us write, in general, an evolution equation

$$(3.1) \quad \begin{aligned} \dot{z} &= A(\alpha)z + F(z, \alpha) \\ F(z, \alpha) &= O(|z|^2) \end{aligned}$$

in a certain Banach space X , where $A(\alpha)$ is a closed operator from X to X with domain $Y \subset X$, Y being a Banach space continuously and densely contained in X . Assume that

$$F: Y \times (-\delta, \delta) \rightarrow X$$

is sufficiently smooth, and further assume that $A(\alpha)$ has only eigenvalues which have the following properties;

- i) A pair of complex conjugate eigenvalues $\lambda(\alpha)$ and $\overline{\lambda(\alpha)}$ such that

$$\begin{aligned} \lambda(\alpha) &= \mu(\alpha) + i\omega(\alpha), \quad \omega(0) = \omega_0 > 0 \\ \mu(0) &= 0, \quad \mu'(0) \neq 0. \end{aligned}$$

- ii) (H.2) holds

Then we have, as usual, the spectral decomposition

$$X = P \oplus Q,$$

where P is the two-dimensional eigenspace of $A(\alpha)$ corresponding to $\lambda(\alpha)$ and $\overline{\lambda(\alpha)}$. By making use of this decomposition we rewrite as (3.1)

$$(3.2) \quad \begin{cases} \dot{x} = A_P(\alpha)x + F_P(x, y, \alpha), \\ \dot{y} = A_Q(\alpha)y + F_Q(x, y, \alpha), \end{cases}$$

where $z = x + y \in P \oplus Q$ and $A_P(\alpha)$ (resp. $A_Q(\alpha)$) and $F_P(x, y, \alpha)$ (resp. $F_Q(x, y, \alpha)$) are restrictions of $A(\alpha)$ and $F(x, y, \alpha)$ to P (resp. Q). Let us denote the matrix representation of $A_P(\alpha)$ by

$$\begin{bmatrix} \mu(\alpha) & -\omega(\alpha) \\ \omega(\alpha) & \mu(\alpha) \end{bmatrix}.$$

Expanding (3.2) in the Taylor series we have

$$\begin{aligned} \dot{x}_1 &= \mu(\alpha)x_1 - \omega(\alpha)x_2 + \sum_{j=2}^{\infty} B_1^j(x, y, \alpha), \\ \dot{x}_2 &= \omega(\alpha)x_2 + \mu(\alpha)x_1 + \sum_{j=2}^{\infty} B_2^j(x, y, \alpha), \\ \dot{y} &= A_Q(\alpha)y + \sum_{j=2}^{\infty} B_Q^j(x, y, \alpha) \\ &= A_Q(\alpha)y + J(\alpha)x^2 + N(\alpha)xy + E(\alpha)y^2 + \Gamma_3(x, \alpha)y^3 + \dots, \end{aligned}$$

which, in polar coordinates $\mathbf{x}=(r\cos\theta, r\sin\theta)$, becomes

$$(3.3) \quad \begin{cases} \dot{r} = F_1(\theta, \alpha)\mathbf{y}^2 + r\{\mu(\alpha) + G_2(\theta, \mathbf{y}, \alpha)\mathbf{y}\} + r^2C_3(\theta, \mathbf{y}, \alpha) + r^3C_4(\theta, \mathbf{y}, \alpha) + \dots \\ \dot{\theta} = \omega_0 + rD_3(\theta, \mathbf{y}, \alpha) + r^2D_4(\theta, \mathbf{y}, \alpha) + \dots \\ \dot{\mathbf{y}} = \text{as above but with } \mathbf{x}=(r\cos\theta, r\sin\theta). \end{cases}$$

Then let us define K by

$$K = K^* + K^{**},$$

$$K^* = \frac{1}{2\pi} \int_0^{2\pi} \{C_4(\theta, 0, 0) - \frac{1}{\omega_0} C_3(\theta, 0, 0)D_3(\theta, 0, 0)\} d\theta,$$

$$K^{**} = \frac{1}{2\pi} \int_0^{2\pi} w^*(\theta)J(0)(\cos\theta, \sin\theta)^2 d\theta,$$

where $w^*(\theta)$ is the unique 2π -periodic solution of

$$(3.4) \quad G_2(\theta, 0, 0) + \dot{w}^*(\theta)\omega_0 + w^*(\theta)A_Q(0) = 0.$$

As is stated in [1], note that for each $\alpha \in (-\delta, \delta)$, $J(\alpha)$ is a bilinear form in the x -space \mathbf{R}^2 taking values in the \mathbf{y} -space; in the above definition $J(0)$ acts on the point $(\cos\theta, \sin\theta) \in \mathbf{R}^2$. Since $G_2(\theta, 0, 0)$ arises as a coefficient of \mathbf{y} in the differential equation involving \dot{r} , $G_2(\theta, 0, 0)$ for each θ is linear functional on \mathbf{y} . Also note that the property $K \neq 0$ depends on the differential equation at $\alpha = 0$.

THEOREM (S. -N. Chow and J. Mallet-Paret). *Suppose that there exists a center manifold taking value in $Q \cap Y$. If $\mu'(0)K < 0$, then the Hopf bifurcation is stable.*

Now let us write (1.6) in polar coordinates as

$$(3.5) \quad \begin{cases} \dot{r} = \mu(\alpha)r + \frac{1}{2} \{II_1[N(U)]\cos\theta - II_2[N(U)]\sin\theta\}, \\ \dot{\theta} = \omega(\alpha) - \frac{1}{2r} \{II_1[N(U)]\sin\theta + II_2[N(U)]\cos\theta\}, \\ \dot{W} = \text{as in (1.6) but with } (u, v) = (r\cos\theta, r\sin\theta). \end{cases}$$

Then,

$$C_3(\theta, 0, 0) = C_4(\theta, 0, 0) = 0$$

and so

$$K^* = 0.$$

In order to calculate K^{**} we first determine $J(0) (\cos \theta, \sin \theta)^2$ and $G_2(\theta, 0, 0) W$. But these are easily obtained as

$$(3.6) \quad J(0) (\cos \theta, \sin \theta)^2 = \text{col } (J_1(0) (\cos \theta, \sin \theta)^2, \dots, J_d(0) (\cos \theta, \sin \theta)^2)$$

with

$$(3.7) \quad J_j(0) (\cos \theta, \sin \theta)^2 = 4 \sum_{k=1}^d a_{jk} (\Phi_j \cos \theta - \Psi_j \sin \theta) (\Phi_k \cos \theta - \Psi_k \sin \theta) \cos^2 n_0 x$$

and

$$(3.8) \quad G_2(\theta, 0, 0) W$$

$$= \sum_{j=1}^d \sum_{k=1}^d a_{jk} \{ (e_1 \Phi_j + e_2 \Psi_j) \{ \cos \theta - (e_2 \Phi_j + e_3 \Psi_j) \sin \theta \} \cdot \{ (\Phi_j \cos \theta - \Psi_j \sin \theta) \int_0^\pi w_k(x) \cos^2 n_0 x dx \} + (\Phi_k \cos \theta - \Psi_k \sin \theta) \int_0^\pi w_j(x) \cos^2 n_0 x dx \}.$$

As in [1] let us write $G_2(\theta, 0, 0)$ as a Fourier series:

$$G_2(\theta, 0, 0) = \sum_{n=-\infty}^{\infty} g_n e^{in\theta}, \quad g_n \in (\mathcal{Q} \cap \mathbf{H}_N^2)^*.$$

By expanding $w^*(\theta)$ as a Fourier series

$$w^*(\theta) = \sum_{n=-\infty}^{\infty} w_n e^{in\theta},$$

inserting this into (3.4) and equating coefficients, we arrive at

$$w_n = -g_n (A_Q + in\omega_0)^{-1},$$

where A_Q is the restriction of $D(0)(d/dx)^2 + A(U)$ to \mathcal{Q} . Then

$$(3.9) \quad K^{**} = \frac{1}{2\pi} \int_0^{2\pi} \sum e^{in\theta} w_n [J(0) (\cos \theta, \sin \theta)^2] d\theta$$

$$= -\frac{1}{2\pi} \int_0^{2\pi} \sum e^{in\theta} g_n (A_Q + in\omega_0)^{-1} [J(0) (\cos \theta, \sin \theta)^2] d\theta.$$

Since

$$\cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2} \quad \text{and} \quad \sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2i},$$

we have

$$(3.10) \quad g_0(W) = \frac{1}{2} \sum_{j=1}^d \sum_{k=1}^d a_{jk}(e_1\Phi_j + e_2\Psi_j) \int_0^\pi (\Phi_j w_k + \Phi_k w_j) \cos^2 n_0 x dx \\ + \frac{1}{2} \sum_{j=1}^d \sum_{k=1}^d a_{jk}(e_2\Phi_j + e_3\Psi_j) \int_0^\pi (\Psi_j w_k + \Psi_k w_j) \cos^2 n_0 x dx,$$

$$(3.11) \quad g_1(W) = \overline{g_{-1}(W)} = 0,$$

$$(3.12) \quad g_2(W) = \overline{g_{-2}(W)} \\ = \frac{1}{4} \sum_{j=1}^d \sum_{k=1}^d a_{jk}(e_1\Phi_j + e_2\Psi_j) \int_0^\pi (\Phi_j w_k + \Phi_k w_j) \cos^2 n_0 x dx \\ + \frac{i}{4} \sum_{j=1}^d \sum_{k=1}^d a_{jk}(e_2\Phi_j + e_3\Psi_j) \int_0^\pi (\Phi_j w_k + \Phi_k w_j) \cos^2 n_0 x dx \\ + \frac{i}{4} \sum_{j=1}^d \sum_{k=1}^d a_{jk}(e_1\Phi_j + e_2\Psi_j) \int_0^\pi (\Psi_j w_k + \Psi_k w_j) \cos^2 n_0 x dx \\ - \frac{1}{4} \sum_{j=1}^d \sum_{k=1}^d a_{jk}(e_2\Phi_j + e_3\Psi_j) \int_0^\pi (\Psi_j w_k + \Psi_k w_j) \cos^2 n_0 x dx$$

and

$$(3.14) \quad g_n(W) = \overline{g_{-n}(W)} = 0 \quad \text{for } n=3, 4, \dots$$

Next we determine

$$F(\theta, x) = (A_Q + in\omega_0)^{-1}(\mathcal{J}(0) (\cos \theta, \sin \theta)^2) \quad \text{for } n=0, \pm 2,$$

that is, find F of

$$(A_Q + in\omega_0)F = \mathcal{J}(0)(\cos \theta, \sin \theta)^2,$$

which is equivalent to

$$(3.14) \quad \begin{cases} D(0)F_{xx} + in\omega_0 F = A(\bar{U})F = \mathcal{J}(0)(\cos \theta, \sin \theta)^2 \\ F_x(\theta, 0) = F_x(\theta, \pi) = 0, \end{cases}$$

because $J(0)(\cos \theta, \sin \theta)^2 \in \mathcal{Q} \cap \mathbf{H}_N^2([0, \pi])$. From (3.7) we have

$$J_j(0)(\cos \theta, \sin \theta)^2 = a_j(\theta) + a_j(\theta) \cos 2n_0 x,$$

where

$$a_j(\theta) = 2 \sum_{k=1}^d a_{jk} (\Phi_j \cos \theta - \Psi_j \sin \theta) (\Phi_k \cos \theta - \Psi_k \sin \theta).$$

By expanding F as

$$F = \sum_{k=0}^{\infty} F_k \cos kx,$$

inserting this into (3.14) and equating coefficients, we have, for $n=0, \pm 2$,

$$(3.15) \quad \begin{aligned} F &= (A_Q + in\omega_0)^{-1} J(0)(\cos \theta, \sin \theta)^2 \\ &= (A(\bar{U}) + in\omega_0)^{-1} \mathbf{a}(\theta) + (A(\bar{U}) + in\omega_0 - 4n_0^2 D(0))^{-1} \mathbf{a}(\theta) \cos 2n_0 x, \end{aligned}$$

where

$$\mathbf{a}(\theta) = \text{col}(a_1(\theta), \dots, a_d(\theta)).$$

Consequently we have

$$\begin{aligned} K^{**} &= \frac{1}{2\pi} \int_0^{2\pi} g_0 [A(\bar{U})^{-1} \mathbf{a}(\theta) + (A(\bar{U}) - 4n_0^2 D(0))^{-1} \mathbf{a}(\theta) \cos 2n_0 x] d\theta \\ &\quad - \frac{1}{\pi} \int_0^{2\pi} \text{Re} e^{2\theta i} \{g_2 [(A(\bar{U}) + 2i\omega_0)^{-1} \mathbf{a}(\theta) \\ &\quad + (A(\bar{U}) + 2i\omega_0 - 4n_0^2 D(0))^{-1} \mathbf{a}(\theta) \cos 2n_0 x]\} d\theta = I_1 + I_2. \end{aligned}$$

Since

$$\frac{1}{2\pi} \int_0^{2\pi} a_j(\theta) d\theta = \sum_{k=1}^d a_{jk} (\Phi_j \Phi_k + \Psi_j \Psi_k),$$

by putting

$$\mathbf{b} = \text{col}(b_1, \dots, b_d) \text{ with } b_j = \sum_{k=1}^d a_{jk} (\Phi_j \Phi_k + \Psi_j \Psi_k),$$

$$\mathbf{b}^{(1)} = A(\bar{U})^{-1}\mathbf{b} \quad \text{and} \quad \mathbf{b}^{(2)} = (A(\bar{U}) - 4n_0^2 D(0))^{-1}\mathbf{b},$$

we have

$$\begin{aligned} I_1 &= -g_0[\mathbf{b}^{(1)}] - g_0[\mathbf{b}^{(2)} \cos 2n_0 x] \\ &= -\frac{1}{2} \sum_{j=1}^d \sum_{k=1}^d a_{jk} (e_1 \Phi_j + e_2 \Psi_j) (\Phi_j b_k^{(1)} + \Phi_k b_j^{(1)}) \\ &\quad - \frac{1}{2} \sum_{j=1}^d \sum_{k=1}^d a_{jk} (e_2 \Phi_j + e_3 \Psi_j) (\Psi_j b_k^{(1)} + \Psi_k b_j^{(1)}) \\ &\quad - \frac{1}{4} \sum_{j=1}^d \sum_{k=1}^d a_{jk} (e_1 \Phi_j + e_2 \Psi_j) (\Phi_j b_k^{(2)} + \Phi_k b_j^{(2)}) \\ &\quad - \frac{1}{4} \sum_{j=1}^d \sum_{k=1}^d a_{jk} (e_2 \Phi_j + e_3 \Psi_j) (\Psi_j b_k^{(2)} + \Psi_k b_j^{(2)}). \end{aligned}$$

Since

$$\frac{1}{\pi} \int_0^{2\pi} e^{2\theta i} a_j(\theta) d\theta = \sum_{k=1}^d a_{jk} (\Phi_j - i\Psi_j) (\Phi_k - i\Psi_k),$$

by putting

$$\begin{aligned} \mathbf{c} &= \text{col}(c_1, \dots, c_d) \quad \text{with} \quad c_j = \sum_{k=1}^d a_{jk} (\Phi_j - i\Psi_j) (\Phi_k - i\Psi_k), \\ \mathbf{c}^{(1)} &= (A\bar{U}) + 2i\omega_0)^{-1}\mathbf{c} \quad \text{and} \quad \mathbf{c}^{(2)} = (A(\bar{U}) + 2i\omega_0 - 4n_0^2 D(0))^{-1}\mathbf{c}, \end{aligned}$$

we have

$$\begin{aligned} I_2 &= -\text{Re } g_2[\mathbf{c}^{(1)}] - \text{Re } g_2[\mathbf{c}^{(2)} \cos 2n_0 x] \\ &= -\frac{1}{4} \text{Re} \sum_{j=1}^d \sum_{k=1}^d a_{jk} [\{ (e_1 \Phi_j + e_2 \Psi_j) + i(e_2 \Phi_j + e_3 \Psi_j) \} (\Phi_j c_k^{(1)} + \Phi_k c_j^{(1)}) \\ &\quad + i \{ (e_1 \Phi_j + e_2 \Psi_j) + i(e_2 \Phi_j + e_3 \Psi_j) \} (\Psi_j c_k^{(1)} + \Psi_k c_j^{(1)})] \\ &\quad - \frac{1}{8} \text{Re} \sum_{j=1}^d \sum_{k=1}^d a_{jk} [\{ (e_1 \Phi_j + e_2 \Psi_j) + i(e_2 \Phi_j + e_3 \Psi_j) \} (\Phi_j c_k^{(2)} + \Phi_k c_j^{(2)}) \\ &\quad + i \{ (e_1 \Phi_j + e_2 \Psi_j) + i(e_2 \Phi_j + e_3 \Psi_j) \} (\Psi_j c_k^{(2)} + \Psi_k c_j^{(2)})]. \end{aligned}$$

Consequently we have

THEOREM 3.

$$\begin{aligned}
K = & -\frac{1}{4} \sum_{j=1}^d \sum_{k=1}^d a_{jk} (e_1 \Phi_j + e_2 \Psi_j) \{2(\Phi_j b_k^{(1)} + \Phi_k b_j^{(1)}) + (\Phi_j b_k^{(2)} + \Phi_k b_j^{(2)})\} \\
& -\frac{1}{4} \sum_{j=1}^d \sum_{k=1}^d a_{jk} (e_2 \Phi_j + e_3 \Psi_j) \{2(\Psi_j b_k^{(1)} + \Psi_k b_j^{(1)}) + (\Psi_j b_k^{(2)} + \Psi_k b_j^{(2)})\} \\
& -\frac{1}{4} \operatorname{Re} \sum_{j=1}^d \sum_{k=1}^d a_{jk} \{(e_1 \Phi_j + e_2 \Psi_j) + i(e_2 \Phi_j + e_3 \Psi_j)\} \cdot \\
& \quad \cdot \{(\Phi_j c_k^{(1)} + \Phi_k c_j^{(1)}) + i(\Psi_j c_k^{(1)} + \Psi_k c_j^{(1)})\} \\
& -\frac{1}{8} \operatorname{Re} \sum_{j=1}^d \sum_{k=1}^d a_{jk} \{(e_1 \Phi_j + e_2 \Psi_j) + i(e_2 \Phi_j + e_3 \Psi_j)\} \cdot \\
& \quad \cdot \{(\Phi_j c_k^{(2)} + \Phi_k c_j^{(2)}) + i(\Psi_j c_k^{(2)} + \Psi_k c_j^{(2)})\},
\end{aligned}$$

where

$$\begin{aligned}
e_1 &= \langle \Psi, \Psi \rangle / (\langle \Phi, \Phi \rangle \langle \Psi, \Psi \rangle - \langle \Phi, \Psi \rangle^2), \\
e_2 &= -\langle \Phi, \Phi \rangle / (\langle \Phi, \Phi \rangle \langle \Psi, \Psi \rangle - \langle \Phi, \Psi \rangle^2), \\
e_3 &= \langle \Phi, \Phi \rangle / (\langle \Phi, \Phi \rangle \langle \Psi, \Psi \rangle - \langle \Phi, \Psi \rangle^2), \\
\mathbf{b}^{(1)} &= A(\bar{U})^{-1} \mathbf{b}, \quad \mathbf{b}^{(2)} = (A(\bar{U}) - 4n_0^2 D(0))^{-1} \mathbf{b}
\end{aligned}$$

with

$$\mathbf{b} = \operatorname{col} (b_1, \dots, b_d), \quad b_j = \sum_{k=1}^d a_{jk} (\Phi_j \Phi_k + \Psi_j \Psi_k)$$

and

$$\mathbf{c}^{(1)} = (A(\bar{U}) + 2i\omega_0)^{-1} \mathbf{c}, \quad \mathbf{c}^{(2)} = (A(\bar{U}) + 2i\omega_0 - 4n_0^2 D(0))^{-1} \mathbf{c}$$

with

$$\mathbf{c} = \operatorname{col} (c_1, \dots, c_d), \quad c_j = \sum_{k=1}^d a_{jk} (\Phi_j - i\Psi_j)(\Phi_k - i\Psi_k).$$

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